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## AUTOMATED LOADER ARM ABSTRACT OF THE DISCLOSURE

A container handling system is disclosed, including subsystems for accessing, grabbing, lifting and tipping collection containers into the charging compartment of a collection vehicle, or the like, and thereafter returning emptied containers to their pick up locations. The invention includes an automated, short radius pivot arm capable of operation in close quarters which may further be mounted to and operated by means of a hydraulic rotary actuator. Electronic control is also provided.